### TI's new C2000<sup>™</sup> real-time controller series: TMS320F28002x

2020 Q2



### Agenda

- C2000<sup>™</sup> + TMS320F28002x introduction
- C2000<sup>™</sup> Generation 3 Enhancements
- Available C2000<sup>™</sup> F28002x-based solutions + how to get started
- C2000<sup>™</sup> peripheral deep dive
  - FSI: What can you do with a low-latency 200Mbps serial interface?
  - CLB: Defy conventional logic with customizable on-chip peripherals
- C2000<sup>™</sup> Digital Control Library Overview
  - Non-linear PID (new in F28002x)



### F28002x real-time controllers:

Real-time control meets system cost optimization and performance scalability





### The latest in extensive real-time control portfolio

- The F28002x series builds on the third generation improvements introduced in the F2838x, F2837x and F28004x series.
- The F28002x series allows to scale from high-end to mid-end to **low-end** while maintains differentiation and performance.
- The C2000 portfolio provides **pin-to-pin** and code compatibility, alleviating effort to scale products performance.
- It's easy to migrate and build a range of products on similar technology, enabling a sustainable platform solution.





### C2000<sup>™</sup> F28002x

#### Differentiation

#### Optimized for Low-Cost, High-Performance Power Control Applications Streamlined performance

- 100MHz / 128 kB flash / 28 kB SRAM
- 100 MIPS DSP Processing Power
- Floating Point, Trigonometric Math Unit, NLPID & Division acceleration

#### Advanced actuation and design flexibility

- 4<sup>th</sup> gen ePWM enables implementation of the most advanced switching techniques for increased efficiency and power density
- Enhanced crossbars provide flexibility in combining inputs, outputs and internal resources for advanced control and protection mechanisms

#### Premium analog

- 2 12-bit 3.45MSPS ADC with post processing and threshold actions
- 4 Windowed Comparator Sub-system

#### **Rich digital options**

• CAN, QEP, Position Manager, UART, SPI, LIN, I2C, PMBus, FSI, etc.

#### Perfect portfolio

- Architecture compatible with F28004x, F2807x, and F2837x
- Pin-pin compatible with 64-pin F28004x

LaunchPad

Upgrade for popular Piccolo F2803x and F2802x

#### Tools



Experimenter's Kit Part Number: TMDSCNCD280025C

'20Q2

Part Number: LAUNCHXL-F280025C '21Q2

#### FCS: Now APL: April'20 RTM: October'20

F28002x		Temperatures		125C	Q100	
Sensing				Actuation	1	
ADC1: 12-bit, 3.45 MSPS, 8ch	C28x™ DSP core 100 MHz FPU, FastDIV TMU w/ NLPID		7x ePWM Modules		iles	
ADC2: 12-bit, 3.45 MSPS, 8ch			144.0			
4x CMPSS: 12-bit DAC				Fault Trip Zones		
8 COMP, 8 digital filters			Connectivity			
Temperature Sensor	6ch DMA CRC & HWBIST		1x UART, 2x LIN/UART		UART	
2x eQEP				1 v 120 1 v PMBus		
3x eCAP , 1x HRCAP						
				ZX SPI, IX F		
				1x CAN 2.08	3	
Configurable Logic Block	Mer	nory	Power & Clocking			
2 Tiles	128 kB FLASH (1 bank) +ECC 2x 10 MHz OSC					
	24 kB SR	AM +ECC		1 2V VREG		
System Modules	R	М	P	OR/BOR Prote	ction	
3x 32-bit CPU Timers	128-bit Dual S	Security Zones				
NMI Watchdog Timer	Host Interface	Controller (HIC)		Debug		
192 Interrupt PIE			cJT	AG / Real-time	JTAG	
				ERAD		







# **C2000<sup>™</sup> generation 3 enhancements**

F2838x, F2837x, F2807x, F28004x, **F28002x** 



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### F28002x comparison table

### F28002x Highlights

- F28002x is a new and improved migration device for the popular F2802x/03x devices at an even lower cost
- FPU (floating point) + FastDIV functionality
- Accelerators (TMU, DMA)
  - NonLinear PID to boost efficiency for applications that demand especially fast transient response
- 2 ADCs with individual sample and hold, post processing and more flexible triggering
- NEW Host Interface Controller
- Feature rich comparator sub-system
- Variety of serial channels: FSI, PMBus, LIN, I2C, SPI, CAN, QEP, more

#### Comparison of F28002x series with Gen 2 and Gen 3 series

	GE	GEN 3		N 2
	F280025	F280049	F28027	F28035
Total MIPS	100	200	60	120
CPU	100	100	60	60
FPU	YES + FastDIV	YES	NO	NO
TMU	YES + NLPID	YES	NO	NO
DMA	YES	YES	NO	NO
CLA	NO	Type-2	NO	Type-1
Flash (KB)	128	256	64	128
RAM (KB)	24	100	20	20
ADC	2x12-bit	3x 12 bit	1X 12-bit	1x 12-bit
Sample & Hold	2	3	2	2
ADC Channels	16	21	16	16
ADC Post Processing	YES	YES	NO	NO
Comparators	4	7	2	3
CMPSS	CMPSS	CMPSS	NO	NO
Sigma-Delta Filter	0	4	0	0
ePWM Technology	Type-4	Type-4	Type-2	Type-2
PWM Channels	14	16	14	14
HRPWM Channels	8	16	7	7
CLB	YES	YES	NO	NO
HIC	YES	NO	NO	NO
QEP	2	2	0	1
CAN	1	2	0	1
UART	3	2	1	1
LIN	2	1	0	0
12C	2	1	1	1
SPI	2	2	1	2
FSI	1	1	0	0
PMBus	1	1	0	0
Packages	48, 64, 80	56,64,100	38,48	56, 64, 80
1ku price	\$1.52 - \$3.30	\$4.85 - \$7.95	\$2.20 - \$4.08	\$3.05 - \$5.80



### **C2000<sup>™</sup> Generation 3 Enhancements**

New process technology allows for more features: accelerators (TMU), memory, peripherals, lower power consumption.

Modules	Enhancement
ePWM	flexible load capability, DB generation, advance trip-zone functionality, more high resolution PWMs
X-BAR	flexible crossbars for premium advanced control and protection mechanisms
ADC	Improvements to sensing capability through additional ADCs, and ADC post-processing hardware
CMPSS	new Comparator Subsystem (CMPSS) with windowed comparators
FSI	latest peripherals like high-speed Fast Serial Interface (FSI) at up to 200 Mbps
CLB	new Configurable Logic Block (CLB) provides further system integration and customization
Memory	enhancements with addition of ECC, parity, dual-zone security memory and DMA



# C2000<sup>™</sup> F28002x solutions & get started



### Two phase, interleaved LLC DC-DC Converter for EV/HEV Applications

Design Status: F28002x support DPSDK, legacy F2837xD support in ControlSUITE



Texas Instruments

#### **Features**

- Two-phase interleaved LLC resonant DC-DC solution showcasing type-4 PWM, ADC and CMPSS features on C2000 real-time controller
- V<sub>in</sub>: 370V 410VDC, V<sub>out</sub>: 12VDC, I<sub>out</sub>: 42.5A, P<sub>out</sub>: 500W
- Peak efficiency: 94.5%, Efficiency > 90% (loads >10%)
- Switching frequency: 200-350 kHz (Resonant 250 kHz)
- · Software based current sharing
- Configurable phase shedding, soft-start, and SR limits
- · Fault protection: primary current, output voltage and current
- PMBUS library can be added

#### **Applications**

- EV 400V to 12V DC-DC
- Server power supplies
- Telecom power supplies

#### **Tools & Resources**

- TIDM-1001
- Design Guide
- **Design Files:** Schematics, BOM, Gerbers, Software, etc.
- Device Datasheets:
  - <u>TMS320F280025C</u>
  - <u>UCD7138</u> - UCC27524

#### Benefits

- Cost effective F28002x device
- Type-4 PWM enables control of multi-phase resonant converters without SW overhead and constraints
- Current balancing with no additional hardware achieves << 5% phase mismatch
- PowerSUITE GUI and SDK support enables easy evaluation and development



### **Encoder based Servo Drive**

#### Features

- · Low-cost, single-chip high-voltage servo drive
- Fast Current Loop FOC
  - PWM latency and FOC execution time signally improve by using Floating Point Unit (FPU), Trigonometric Math Unit (TMU) and Fast Integer Division Unit (FINTDIV)
  - < 2.0us current loop (PWM update), > 96% modulation index to achieve higher speeds
- Dynamic analysis using SFRA
  - Noise is injected into the current loop and output response is measured/ analyzed

### Applications

- · Industrial servo drives
- Factory automation and control
- Robotics

#### **Tools & Resources**

MotorControl SDK

 Key TI Device: TMS320F280025C

- Development Board:
  - TMDXCNCD28025C
  - TMDXIDDK379D

#### Benefits

- Cost effective F28002x real-time controller
- · Improve current loop stability at higher speeds
- Reduce inverter power dissipation
- Easily measure performance in terms of stability and closed loop bandwidth





### **Fast Current Loop Performance**





### C2000<sup>™</sup> peripheral deep dive: What can you do with a low-latency 200Mbps serial interface?

An introduction to Fast Serial Interface (FSI)



### **Standard communication interfaces**



Uniquely meets the three key criteria:

- Very low signal count
- High bandwidth, low latency
- Standard LVCMOS IO buffer



### **Fast Serial Interface overview**

- Low-latency, high-speed communication
  - Double data rate
  - Minimal packet header and footer
- Built for isolated control topologies
  - Uni-directional signals
  - Single or double data lines
- Robust
  - 8-bit Hardware CRC
  - Line break detection
  - Skew compensation
- Flexible Topologies
  - Point-to-point
  - Star
  - Daisy chain





### **Fast Serial Interface overview**



The TX and RX ports work asynchronously to each other.

- 100 Mbps 200 Mbps (1-2 data lines)
- Ideal for Isolation; 4-6 unidirectional signals
- Full-duplex communication
- No fixed master and slave structure
- Flexible topologies



### **TMDSFSIADAPEVM**

#### Features

### Solution scope

- System
  - Validates the FSI link and system capabilities
  - Enables isolated control topologies
- Hardware
  - Adapter board to enable C2000 MCU development
  - Compatible with all FSI enabled EVMs
    - Works in conjunction with BoosterPacks and controlCARDs
  - Supports LVDS (100/200) Mbps
  - Supports RS485 (100Mbps)
  - Uses standard Cat-5 Cable
- Software
  - SW example fast data transfer across isolation links
  - Examples in C2000Ware

### Applications

- Distributed control architectures
- Servo Drives
- Grid Infrastructure
- Low cost fast serial network for automation
- Enables low cost peripheral expansion and smart sensing applications

### **Benefits**

- High-speed allowing more data, fewer channels required, and distributed control architectures
- Low channel count to reduce cost of isolation



http://www.ti.com.cn/cn/lit/ug/swru555/swru555.pdf



### TIDM-02006 – Distributed multi-axis servo drive over Fast Serial Interface (FSI)

#### **Features**

- Demonstrate high-speed (100mbps) communication using fast serial interface (FSI) for real-time control
- Implement position and velocity control loops for all slave axes on F2838x based master node, torque/current loops on F28004x based slave nodes
- Up to 16 axes. Simultaneous start and stop control. Low latency (high bandwidth) and precision control of distributed multi-axis servo drive system
  - 1uS/2uS sampling to PWM latency with F2838x/F28004x respectively
  - <2uS command jitter among slave nodes</li>
- Leverage F2838x's multi-cores. Speed and position control over FSI for all slave nodes on CPU1, Main axis control on CPU2, EtherCAT communication with host PC on CM.
- Integrated SFRA tool on both F28004x and F2838x to support speed and current loop tuning

#### Target Applications

- · Industrial servo drives
- · Factory automation and control
- Robotics

#### Tools & Resources

- <u>TIDM-02006</u>
- Design Guide
- Design Files: Design Files, Software
- Key TI Device:
  - TMS320F280049C → TMS320F280025C
  - TMS320F28388D

- Development Boards:
  - TMDXIDDK379D
  - TMDSCNCD28388D
  - LAUNCHXL-F280049C
  - BOOSTXL-3PHGANINV
  - TMDSFSIADAPEVM

#### **Benefits**

- High control performance , high-speed communication with low jitter, and ease of use
- · Easy to tune control loops using SFRA tool
- Reduced system cost (fewer isolated channels) and increased reliability due to fast serial interface (FSI)
- Reduced development time due to built-in incremental software build levels





### C2000<sup>™</sup> peripheral deep dive: Defy conventional logic with customizable on-chip peripherals

**Configurable Logic Block (CLB)** 



# Integrate custom logic and augment peripheral capability in your real-time MCU applications

Customized logic is usually done in a system by adding FPGAs, CPLDs, or external logic. These systems almost always still include a traditional microcontroller as well.



C2000 Configurable Logic Block (CLB) enables customization in a microcontroller based real-time control system while eliminating or reducing the size of the FPGA, CPLD, or external logic



### What can be done with the CLB?

- Advanced PWM protection schemes for reliability and safety
- Complex PWM generation, burst mode PWM, and periodic blanking
- Complex signal capture and sequence detection
- Logic based filters and signal conditioning
- Task profiling and time threshold monitoring
- Highly customized general purpose outputs
- Pulse train outputs
- Absolute encoder interfaces
- What can you imagine?



### C2000 configurable logic block peripheral



Configurable Logic Block gives the ability to:

- Build logic around and augment existing on-chip peripherals like ePWM, eCAP, eQEP, and GPIOs
- Implement independent custom logic



### **CLB** structure



### 4-input LUT (LUT4)

- Look Up Table
- 4 inputs and one output
- Any function of 4 inputs (or less) can be realized.
- C syntax

 4 input AND
 O = i1 & i2 & i3 & i0

 3 input OR
 O = i1 | i2 | i0

 More complex
 O = (!i2 & (i1 | i0))





LUT4







- Allows implementing Finite State Machines (FSM) of up to 4 states
  - One 4-state FSM or Two 2-state FSMs
- E0 and E1: Two inputs control FSM\_OUT or either of the states S0 and S1.
- S0 and S1 are two state bits that have independent state control equations.



**FSM** 

### **Counter block**





#### Inputs

- **RESET** : If high, reset to 0 on the next clock cycle.
- **MODE\_0** : counting operation only when this input is high.
- **MODE\_1** : High  $\rightarrow$  Increment, Low  $\rightarrow$  Decrement
- EVENT : Load, Right/Left shift, Add/subtract predefined value

#### Outputs

- **ZERO** : High when counter value is 0.
- MATCH1 : High when counter value equals MATCH1
- MATCH2 : High when counter value equals MATCH2



### **HLC** architecture

(high-level-controller)



#### HLC Instructions

**HLC** 

- Mov <src>,<dst>
- Mov\_T1 <src>,<dst>
- Mov\_T2 <src>,<dst>
- ADD <src>,<dst>
- Sub <src>,<dst>
- PUSH <src>
- PULL <src>
- INTR <const:6>

#### <u>Where</u> <src/dst> =

- R0-R3 (HLC Regs)
- C0-C2 (Counter values)



### **CLB advantages vs FPGA and CPLD**

- Integrated into a high-performance fully programmable real-time controller
- Residing inside the C2000 MCU, the CLB has direct access to key CPU and peripheral signals
- Internal signals can be used to supplement or modify logic inside control peripherals and external glue logic
- The simple programmable processor (HLC) facilitates data transfers between CLB and CPU memory. Up to four stored programs can be triggered by low-to-high transition of selected internal CLB signals.
- Timing of CLB signals already designed for the specified CPU frequency; any logic that is created using CLB is guaranteed to meet the timing requirements
- Fully software configurable and can be changed easily in-system



# **C2000 Digital Control Library**

**Nonlinear PID Overview** 



### **Nonlinear PID**



**Classical PID Control** 

Non-linear PID – Current State-of-the-art



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### NLPID system-level benefits (on F28002x and beyond)

- Improved of control performance up to 4x faster transient response
  - Without need to increase sampling/switching frequency (thanks to enhanced instructions in the TMU accelerator)
  - Without need of higher MHz CPU, ultimately saving cost (don't need expensive processor, data converters, etc) and making the most out of available MIPS
  - Especially beneficial for timing critical applications that demand a fast transient response, like server and telecom power and motor control
- Simpler tuning process compared to Look-Up-Tables
  - Single tunable parameter in each path gain scheduling not necessary for NLPID
- Better disturbance rejection and regulation control
  - Saves processing power
  - Improved speed + position control in servo applications
  - Improved voltage regulation in power supply applications



### What Comes in the Box?





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- 海量正品现货,超值线上价格\*
- 定制卷带,随心订购
- 快速批量加入购物车,简单便捷
- 可订购预发布产品,快人一步



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# Thank you!

